

The Riemann Spaces in the Theory of the Navier-Stokes Equations

Valerii Dryuma

Abstract

A geometric approach for integrating the system of Navier-Stokes equations in the Euler and Lagrange variables is proposed.

Keywords: space of the Riemann, tensor Ricci, 6D-metric, Invariants, geodesics, incompressibility.

1 Introduction

The basis of the geometric approach for studying properties of Navier-Stokes system of equations (NS-system) composes the relations $x = f_1(a, b, c, t)$, $y = f_2(a, b, c, t)$, $z = f_3(a, b, c, t)$, $p = h(a, b, c, t)$, where (x, y, z, p) are the local coordinates for variable of pressure p and the variables (a, b, c) – for dual coordinates of individual points of the liquid at each moment of the parameter time t . As a result of elimination of the variables (a, b, c) with the help of the appropriate differentiations, the well-known system of Navier-Stokes equations in Euler variables is obtained

$$\frac{\partial}{\partial \eta} \vec{U} + (\vec{U} \cdot \vec{\nabla}) \vec{U} + -\frac{1}{\rho} \vec{\nabla} P - \mu \Delta \vec{U} = 0, \quad \text{div } \vec{U} = 0, \quad (1)$$

where $\vec{U}$ is the vector of velocity of fluid, ρ is density, and μ is viscosity of fluid.

Similarly, after excluding of the coordinates (x, y, z) from the indicated relations, a system of equations, determining the movement of individual points of the liquid is obtained.

2 Ricci-flat metric associated with the NS-system

The 14D-space in local coordinates $(x, y, z, t, \eta, \rho, m, u, v, w, p, \xi, \chi, n)$ is considered.

Theorem 1. *The metric of the form*

$$\begin{aligned} ds^2 = & 2 dx^2 + 2 dx dy + 2 dx du + 2 dy^2 + 2 dy dz + 2 dy dv + \\ & 2 dz^2 + 2 dz dw + 2 dt dp + 2 d\eta d\xi + 2 d\rho d\chi + 2 dm dn + A dt^2 + \\ & B d\eta^2 + C d\rho^2 + E dm^2, \end{aligned} \quad (2)$$

where

$$\begin{aligned} A = & 2 - U(x, y, z, t) u - V(x, y, z, t) v - W(x, y, z, t) w, \\ B = & \left(-UW + \mu \frac{\partial}{\partial z} U \right) w + \left(-UV + \mu \frac{\partial}{\partial y} U \right) v + \\ & \left(\mu \frac{\partial}{\partial x} U - (U)^2 - P \right) u - Up, \end{aligned} \quad (3)$$

$$\begin{aligned} C = & \left(-VW + \mu \frac{\partial}{\partial z} V \right) w + \left(\mu \frac{\partial}{\partial y} V - (V)^2 - P \right) v + \\ & \left(-UV + \mu \frac{\partial}{\partial x} V \right) u - Vp, \end{aligned} \quad (4)$$

$$\begin{aligned} E = & \left(-\mu \frac{\partial}{\partial x} U - \mu \frac{\partial}{\partial y} V - (W)^2 - P \right) w + \left(-VW + \mu \frac{\partial}{\partial y} W \right) v + \\ & \left(-UW + \mu \frac{\partial}{\partial x} W \right) u - Wp, \end{aligned} \quad (5)$$

is the Ricci-flat on solutions of Navier-Stokes system of equations.

In the Lagrange variables (a, b, c, t) , full system of Navier-Stokes equations looks more complicated and has the form

$$\begin{aligned} & \frac{\partial^2 A}{\partial t^2} + [B, C, P] - \\ & \mu ([B, C, [B, C, A_t]] + [C, A, [C, A, A_t]] + [A, B, [A, B, A_t]]) = 0, \end{aligned} \quad (6)$$

$$\begin{aligned} & \frac{\partial^2 B}{\partial t^2} + [C, A, P] - \\ & \mu ([B, C, [B, C, B_t]] + [B, A, [C, A, B_t]] + [A, B, [A, B, B_t]]) = 0, \end{aligned} \quad (7)$$

$$\begin{aligned} & \frac{\partial^2 C}{\partial t^2} + [A, B, P] - \\ & \mu ([B, C, [B, C, C_t]] + [C, A, [C, A, C_t]] + [A, B, [A, B, C_t]]) = 0, \\ & [A, B, C] - 1 = 0. \end{aligned} \quad (8)$$

3 6D-metric

Theorem 2. *The 6D-Riemann space in coordinates (x, y, z, a, b, c, t) , equipped with a metric of the form*

$$\begin{aligned} ds^2 = & A(a, b, c, t) dx^2 + 2 B(a, b, c, t) dx dy + 2 E(a, b, c, t) dx dz + \\ & dx da + C(a, b, c, t) dy^2 + 2 H(a, b, c, t) dy dz + dy db + \\ & F(a, b, c, t) dz^2 + dz dc \end{aligned} \quad (9)$$

can be used for integration of the equation

$$\begin{aligned} & \frac{\partial}{\partial b} B \frac{\partial}{\partial c} C \frac{\partial}{\partial a} A - \frac{\partial}{\partial b} B \frac{\partial}{\partial a} C \frac{\partial}{\partial c} A - \frac{\partial}{\partial c} C \frac{\partial}{\partial a} B \frac{\partial}{\partial b} A - \frac{\partial}{\partial b} C \frac{\partial}{\partial c} B \frac{\partial}{\partial a} A + \\ & \frac{\partial}{\partial b} C \frac{\partial}{\partial a} B \frac{\partial}{\partial c} A + \frac{\partial}{\partial c} B \frac{\partial}{\partial a} C \frac{\partial}{\partial b} A - 1 = 0, \end{aligned} \quad (10)$$

which is the condition of incompressibility of liquid.

4 Projective duality to the theory of the second order ODE's

$$\frac{d^2}{dx^2} y(x) + a_1 \left(\frac{d}{dx} y(x) \right)^3 + 3 a_2 \left(\frac{d}{dx} y(x) \right)^2 + 3 a_3 \frac{d}{dx} y(x) + a_4 = 0, \quad (11)$$

where $a_i = a_i(x, y)$.

The general integral of this equation has the form $H(x, y, a, b) = 0$ among four variables $(x, y, a, b) = 0$, from which follows a differential equation with respect to the variables a, b

$$\frac{d^2}{da^2}b(a) = g\left(a, b, \frac{d}{da}b(a)\right). \quad (12)$$

Theorem 3. *Two equations $y'' = -a_1(x, y)y'^3 - 3a_2(x, y)y'^2 - 3a_3(x, y)y' - a_4(x, y)$ and $b'' = g(a, b, b')$, where $b' = c$ form a dual pair of equations with a common integral of the form $H(x, y, a, b) = 0$, which with the help of solutions of the equation*

$$\begin{aligned} h(a, b, c) = & \frac{\partial^2}{\partial c \partial a}g(a, b, c) + g(a, b, c) \frac{\partial^2}{\partial c^2}g(a, b, c) - 1/2 \left(\frac{\partial}{\partial c}g(a, b, c) \right)^2 \\ & + c \frac{\partial^2}{\partial c \partial b}g(a, b, c) - 2 \frac{\partial}{\partial b}g(a, b, c) \\ & \frac{\partial^2}{\partial c \partial a}h(a, b, c) + g(a, b, c) \frac{\partial^2}{\partial c^2}h(a, b, c) - \left(\frac{\partial}{\partial c}g(a, b, c) \right) \frac{\partial}{\partial c}h(a, b, c) + \\ & c \frac{\partial^2}{\partial c \partial b}h(a, b, c) - 3 \frac{\partial}{\partial b}h(a, b, c) = 0, \end{aligned} \quad (13)$$

is determined.

5 4D-metric

The geometric method for studying the properties of the NS -system of equations with the theory of second-order ODE 's of normal projective connection of E. Cartan is associated.

Theorem 4. *Geodesic equations of the 4D-space with the metric*

$$\begin{aligned} ds^2 = & (2za_3(x, y) - 2ta_4(x, y))dx^2 + 2(2za_2(x, y) - 2ta_3(x, y))dxdy + \\ & 2dxdz + (2za_1(x, y) - 2ta_2(x, y))dy^2 + 2dydt, \end{aligned} \quad (14)$$

in the coordinates (x, y, z, t) decomposes into two parts.

The first part consists of two equations:

$$\begin{aligned} \frac{d^2}{ds^2}y(s) + a_4(x, y) \left(\frac{d}{ds}x(s) \right)^2 + 2 a_3(x, y) \left(\frac{d}{ds}x(s) \right) \frac{d}{ds}y(s) + \\ a_2(x, y) \left(\frac{d}{ds}y(s) \right)^2 = 0, \end{aligned} \quad (15)$$

$$\begin{aligned} \frac{d^2}{ds^2}x(s) - a_3(x, y) \left(\frac{d}{ds}x(s) \right)^2 - 2 a_2(x, y) \left(\frac{d}{ds}x(s) \right) \frac{d}{ds}y(s) - \\ a_1(x, y) \left(\frac{d}{ds}y(s) \right)^2 = 0. \end{aligned} \quad (16)$$

And the second part has the form of the linear system of equations for the vector $\vec{\Psi} = (\Psi_1 = z(s), \Psi_2 = t(s))$

$$\frac{d^2\vec{\Psi}}{ds^2} + A(x, y) \frac{d\vec{\Psi}}{ds} + B(x, y)\vec{\Psi} = 0, \quad (17)$$

where $\vec{\Psi} = (\Psi_1 = z(s), \Psi_2 = t(s))$ and $A(x, y), B(x, y)$ are the 2×2 matrix-functions.

Corresponding Ricci tensor R_{ij} of the metrics is of the form

$$\begin{aligned} R_{11} &= 2 \frac{\partial}{\partial y} a_4(x, y) - 2 \frac{\partial}{\partial x} a_3(x, y) - 4 a_3(x, y)^2 + \\ &\quad 4 a_4(x, y) a_2(x, y), \\ R_{12} &= -2 \frac{\partial}{\partial x} a_2(x, y) + 2 \frac{\partial}{\partial y} a_3(x, y) - 2 a_2(x, y) a_3(x, y) + \\ &\quad 2 a_4(x, y) a_1(x, y), \\ R_{22} &= -2 \frac{\partial}{\partial x} a_1(x, y) + 2 \frac{\partial}{\partial y} a_2(x, y) + 4 a_1(x, y) a_3(x, y) - \\ &\quad 4 a_2(x, y)^2. \end{aligned} \quad (18)$$

6 Conclusion

This article proposes a geometric approach for constructing exact solutions of the Navier-Stokes equations and studying their properties.

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Valerii Dryuma

Moldova State University, Institute of Mathematics and Computer Science
“Vladimir Andrunachievici”, Chisinau, Republic of Moldova

E-mail: valdryum@gmail.com

ORCID: <https://orcid.org/0009-0002-6581-6650>